

Control Studio & ModBus Configurator

Specification

XDesignPlus

ΣH

## Example: How to operate softMC 3 with HMI







XDesignerPlus			Project Settin			-		
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🎒 New	🕨 🎲 New F	Project Ctrl-	Series	XTOP Series	Vendor	M2I Corr	poration	
			Model	XTOP07TW-LD(-E	E) PLC Mod	del TOP MA	STER	
			-		TOP			
				Series		Model	745	100
			XTOP Serie	9	Name XTOP05MO-ED(-E)	Resolution 320 * 240	Color Mono16Level	Memory 6M
			HTOP Selle	5	XTOP05TQ-ED(-E)	320*240	65536Color	6M
					XTOP05TV-ED-E	640 * 480	65536Color	6M
	· · · · · · · · · · · · · · · · · · ·		10070		XTOP10TS-ED(-E)	800 * 600	65536Color	26M
Project Setting					XTOP10TV-ED(-E)	640 * 480	65536Color	26M
	HMI / PLC Uint				XTOP05TQ-SD	320*240	65536Color	26M
Series XTOP Series	Vendor	MODBUS Organizatio	on		XTOP08TS-SD	800 * 600	65536Color	26M
Model XTOP07TW-LD(-E)	PLC Model	MODBUS-TCP Maste	er(Client)		XTOP10TS-SA/SD	800 * 600	65536Color	26M
	PLC				XTOP10TV-SAVSD	640*480	65536Color	26M
Vendor		Model			XTOP12TS-SA/SD	800 * 600	65536Color	26M
M2I Corporation	MODBUS Serial Master				XTOP15TX-SA/SD	1024 * 768	65536Color	26M
MITSUBISHI Electric Corporation	MODBUS Serial Slave				XTOP05TW-UD(-E)	400 * 240	65536Color	6M
OMRON Industrial Automation	MODBUS-TCP Master(Client)				XTOP07TW-LD(-E)	800 * 480	65536Color	26M
LS Industrial Systems	MODBUS-TCP Slave(Server)				XTOP10TW-UD(-E)	800 * 480	65536Color	26M
MODBUS Organization								
SIEMENS AG.								
Rockwell Automation (AB)								
GE Fanuc Automation								
PANASONIC Electric Works								
YASKAWA Electric Corporation								
Schoolder Electric Industries					Back Next	]	OK	Cancel
KDT Systems								
RS Automation(SAMSUNG)								
HITACHI IES								
FATEK Automation Corporation		Project Setting	1					
DELTA Electronics								
		-			HMI / PLC Uint			
KOYO Electronic Industries		Series 2	CTOP Series		HMI/PLC Uint Vendor M	MODBUS On	ganization	
KOYO Electronic Industries VIGOR Electric Corporation		Series 2 Model 2	CTOP Series	.D(-E)	HMI/PLC Uint Vendor M PLC Model M	MODBUS ON	ganization P Master(Clier	10
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KOYO Electronic Industries VIGOR Electric Corporation Comfile Technology Dongbu(DASAROBOT) ROBOSTAR Bosch Rewoth AG LS MECAPION (Metronix)		Series 2 Model 2	KTOP Series KTOP07TW-L	.D(-E) MODBUS Organ	HMI/PLC Uint Vendor PLC Model N PLC Option PLC Info nization	MODBUS On MODBUS-TC	ganization P Master(Clier	0
KOYO Electronic Industries VIGOR Electric Corporation Comfile Technology Dongbu(DASAROBOT) ROBOSTAR Bosch Rexroth AG LS MECAPION (Metronix)		Series 2 Model 2 Vendor Nar PLC Name	KTOP Series KTOP07TW-L me :	.D(-E) MODBUS Organ MODBUS-TCP (	HMI/PLC Uint Vendor M PLC Model M PLC Option PLC Info nization Master(Client)	MODBUS ON	ganization P Master(Clier	10
KOYO Electronic Industries VIGOR Electric Corporation Comfile Technology Dongbu(DASAROBOT) ROBOSTAR Bosch Rexroth AG LS MECAPION (Metronix) UIGEN Mater (OTIG)		Series 2 Model 2 Vendor Nar PLC Name PLC Alias :	KTOP Series KTOP07TW-L ne : :	.D(-E) MODBUS Organ MODBUS-TCP	HMI/PLC Uint Vendor M PLC Model M PLC Option PLC Info nization Master(Client)	MODBUS ON	ganization P Master(Clier	0
KOYO Electronic Industries VIGOR Electric Corporation Comfile Technology Dongbu(DASAROBOT) ROBOSTAR Bosch Rewoth AG LS MECAPION (Metronix) UIGEN Mater (OTIC)	Back Next	Series 2 Model 2 Vendor Nar PLC Name PLC Alias :	KTOP Series KTOP07TW-L ne : :	D(-E) MODBUS Organ MODBUS-TCP PLC1	HMI/PLC Uint Vendor N PLC Model N PLC Option PLC Info nization Master(Client)	MODBUS Or MODBUS-TC	ganization CP Master(Clier	0
KOYO Electronic Industries VIGOR Electric Corporation Comfile Technology Dongbu(DASAROBOT) ROBOSTAR Bosch Rewroth AG LS MECAPION (Metronix) UIGEM Mater (OTIG)	Back Next	Series 2 Model 2 Vendor Nar PLC Name PLC Alias :	KTOP Series KTOP07TW-L me : ;	.D(-E) MODBUS Organ MODBUS-TCP   PLC1	HMI/PLC Uint Vendor N PLC Model N PLC Option PLC Info nization Master(Client)	MODBUS-TC	ganization CP Master(Clier	10
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KOYO Electronic Industries VIGOR Electric Corporation Comfile Technology Dongbu(DASAROBOT) ROBOSTAR Bosch Rewroth AG LS MECAPION (Metronix) UIGEN Made (ATIG)	Back Next	Series 3 Model 3 Vendor Nar PLC Name PLC Alias : IP Addre Read Po Write Po	KTOP Series KTOP07TW-I me : : ss (PLC) : ft (0~65535) Number(PLC)	D(-E) MODBUS Organ MODBUS-TCP P PLC1 192 \$ 502 502	HMI/PLC Uint Vendor PLC Model PLC Option PLC Info nization Master(Client) PLC Comm Info 168 2	AODBUS-TO	ganization CP Master(Clier	10
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KOYO Electronic Industries VIGOR Electric Corporation Comfile Technology Dongbu(DASAROBOT) ROBOSTAR Bosch Rewroth AG LS MECAPION (Metronix) UIGEN Mades (OTIG)	Back Next	Series 2 Model 2 Vendor Nar PLC Name PLC Alias : IP Addre Read Po Write Po Station Write C Read B Device	kTOP Series           kTOP07TW-I           me :           :           ss (PLC) :           int (0~65535)           number(PLC)           ommand           it Size           Read Type	D(-E) MODBUS Organ MODBUS-TCP P PLC1 192 502 502 0 Preset Single 16 Continuous R	HMI/PLC Uint Vendor PLC Model PLC Option PLC Info nization Master(Client) PLC Comm Info 168 2  C Sequence (Transact Register (0x06) C ead C	toDBUS-TC	ganization CP Master(Clier	10
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Project	HMI Setup Sepcial Bu	ffer Sync				
TOP Setting XTOP07TW-LD(-E)	Use HMI Setup					
PLC Setting COM2 (0)	System Setup PLC S	etup Device Man	ager Interfac	e .		
COM1 (0)			* Ne	etwork		
E Ethernet (1)	- IP address :	192 🗘 168	\$ 2	\$ 201 \$		
- FieldBus (0)	- Subnet mask :	255 \$ 255	\$ 255	¢ 0 ¢		
USB Device (0)	- Gateway :	192 🛟 168	\$ 0	¢1 ¢		
CF/SD Card			* Commu	nication Port		
	+ COM 1		+ C(	DM 2		
	- Boud Rate :	38400	- Bo	ud Rate :	38400 -	
	- Data Bit :	8	- Da	ta Bit :	8 •	
	- Stop Bit :	1	<ul> <li>Sto</li> </ul>	p Bit :	1	
	- Parity Bit :	None	👻 - Pa	rity Bit :	None -	
			- Sig	inal Level :	RS-232C -	
			* HM	II Alias		
	- Alias Name					
			* Bi	uzzer		
	- Buzzer Sound	Enabled	• - Bu	zzer (Interlock)	Disabled -	
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	- Touch Mode :	Normal	• - Toi	uch Sensitivity :	Normal 👻	
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			Import Option
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Symbol Name	Size	Address	
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Symbol Name	Size	Address		Use
A1.POSITIONFEEDBACK	Word	(PLC1)400001		0
JOG_SPEED_int_Write	Word	(PLC1)400003		0
A1.VELOCITYFEEDBACk	Word	(PLC1)400005		0
TARGET_POS_float_Rea	Word	(PLC1)400007		0
A1.ENABLE_int_Write	Word	(PLC1)400009		0
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65535-DefaultTenKey65535      Sub Screen      Global Screen      Joster Screen      J-     1-Master Screen1      Top Frame	Feedback = 8888888.890
□ Left Frame □ Right Frame □ Bottom Frame □ Global Setting □	
Cogging Setting     Setting     Seting     Seting     Setting     Setting	Speed [RPM] <sup>+</sup> ™ 8888 ™ >>
Rages List	

Touch	
Default	Display InterLock Operation Information OPERATION Push on delay 0 + x 100ms No Operation DataType Expression 1 WORD DEC JOG_SPEED_int_Write = JOG_SPEED_int_Write + 10
Touch Tao Type	Down Up     Operation Key Input Sepcial Function     write data size 32 Bit      Operand data size 32 Bit
<ul> <li>Touch</li> <li>Lamp</li> <li>Bit</li> <li>Word</li> <li>N-State</li> <li>Bit Select</li> </ul>	Data Type DEC ODEC ONEX OBCD OPLOAT
Security 0 Security Level Help (F1)	Cancel

Providence	Creat Division Last		
Default	GRAPH STYLE Graph Kind BAR Display Direction	GRAPH   Shape Type	Rectangle •
	GRAPH DATA Graph Address	Symbol - A1.VELOCI	TYFEEDBACK_float_l  (PLC1)400005
	Scan Period Data Type	0 \$ x 500ms FLOAT Data Size	🕲 16bit 🛛 🔘 32bit
	Graph Data Range( Min )	Const -1000.00	-ok-
	Graph Data Range( Max )	Const - 1000.00	-ok
Security			
	÷		
Security Level 0			



## Summary: write all relevant files to create HMI working w softMC

File Name	Created by	Function	For	Comments